

FOUR PORT VIEWER USERS MANUAL



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H&B

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1 Introduction

1.1 Purpose

The purpose of this document is to describe how to use the "Four Port Viewer" application as a tool for calibrating the H&B load cell digital amplifier devices, reading and writing command parameters and monitor weight values measured from the connected devices.

The detailed functionality of the different device command parameters used in the "Four Port Viewer" application will not be explained in this document. The commands are described in detail in other documents covering the functionalities of the different H&B devices.

By having an active internet connection to the PC running the "Four Port Viewer" application, it is possible to access the web pages describing the functionality of different command parameters in details.

In different areas of the "Four Port Viewer" application, help buttons are placed to gain easy access to the command documentation web pages.

If you want to do detailed recordings of streamed data from the load cells to a scope containing the graphical representation of the data recorded, please refer to the more advanced DOP 4 application where also the streamed load cell data can be stored for later analyze.

1.2 Overview

The "Four Port Viewer" application is a tool for calibrating, analyzing and fine-tuning measurement parameters for several of the Hauch & Bach digital amplifier devices for weighing and force measurements, such as the DAD14x, LDM64.1, LDB15x and the LDU series LDU 68.x, LDU 69.1, LDU 78.1 and LDU179.1. All new devices will also be supported by the "Four Port Viewer" application as they are released.

HB Four Port Viewer version 1.3.0.0			- 🗆 X
Channel 1 0.581	Channel 2	Channel 3 0.473	Channel 4
No motion when green:	No motion when green:	No motion when green:	No motion when green:
Set Tare	Set Tare	Set Tare	Set Tare
Commands View	Commands View	Commands View	Commands View
Connect Devices Hardware: ASCII ✓ Baud Rate: 115200 ✓	ChannelDevice Name01LDB15202LDB15203LDB15204LDB152	Device Id Device Version 1520 0140 1520 0140 1520 0140 1520 0140 1520 0140 1520 0140	General Weight Settings ● Net ○ Gross
COM Port 1: COM3 ~	Sub Address 1: 1	Disconnect Device	All Channels Summerized
COM Port 2: COM3 ~	Sub Address 2: 2	Disconnect Device	Set Tare all Channels
COM Port 3: COM3 ~	Sub Address 3: 3	Disconnect Device	Matrix Calibration
COM Port 4: COM3 ~	Sub Address 4: 4	Disconnect Device	
Device: LDB152 wit	h Id: 1520 connected.	I	Exit

The main page consists of four channel groups from which load cell measurement and command settings can be performed. Calibration and tarring of H&B devices can be done from special "Calibration" and "Filter / Tare" dialogs found in the "Commands View" dialog, available for each of the up to four connected devices.

Special dialogs are available for guided 4 load cell matrix calibration to be found in the "Matrix Calibration" dialog.

H&B devices are connected to the "Four Port Viewer" application from the "Connected Devices" group box.

For detailed information on calibration, filtering and command parameters handling, refer to the specific sections covering these issues.



2 Application Startup

The first window which appears after "Four Port Viewer" application startup is the main window. The main window is quite empty until some H&B devices are assigned to one or more of the four channel groups. So, before calibration and measuring can start, the first thing to do after "Four Port Viewer" application startup is to assign one or more H&B devices to one or more of the H&B device channels.

HB Four Port Viewer version 1.3.0.0			- 🗆 X
Channel 1	Channel 2	Channel 3	Channel 4
No motion when green:	No motion when green:	No motion when green:	No motion when green:
Set Tare	Set Tare	Set Tare	Set Tare
Commands View	Commands View	Commands View	Commands View
Connect Devices Hardware: ASCII ~ Baud Rate: 115200 ~	Channel Device Name	Device Id Device Version	General Weight Settings ● Net ○ Gross N
COM Port 1: COM3 ~	Sub Address 1: 1	Connect Device	All Channels Summerized
COM Port 2: COM3 ~	Sub Address 2: 2 ~	Connect Device	Set Tare all Channels
COM Port 3: COM3 ~	Sub Address 3: 3 ~	Connect Device	Matrix Calibration
COM Port 4: COM3 ~	Sub Address 4: 4 ~	Connect Device	
			Exit

Start by defining the devices to be connected to the "Four Port Viewer" application, by configuring the settings in the "Connected Devices" group box.



2.1 Connect Devices

From the "Connect Device" group box, the different H&B devices to be used for communication are selected.

Connect Dev	ices					
Hardware:	ASCII	~	Channel	Device Name	Device Id	Device Version
Baud Rate:	115200	~				
COM Port 1:	COM1	~	Sub Addres	is 1: 1 ~	C	connect Device
COM Port 2:	COM1	~	Sub Addres	ss 2: 2 ~	C	Connect Device
COM Port 3:	COM3	~	Sub Addres	is 3: 1 ~	C	Connect Device
COM Port 4:	COM4	~	Sub Addres	is 4: 0 ~	C	Connect Device
]	

The current version of the "Four Port Viewer" application supports the ASCII and Modbus RTU interface over serial COM ports communication and the CANopen interface over a CANopen bus.

The interface is selected by checking the "ASCII", the "Modbus RTU" or the CANopen interface from the "Hardware" drop down list.

CANopen	~
ASCII	
Modbus RTU	
CANopen	



2.1.1 Select device interface

ASCII:

To select an H&B device using ASCII as interface, select the Hardware type: "ASCII".

Select the correct baud rate for the device.

Select the COM port to which the device is connected.

If more than one H&B device is connected to the same COM port, a specific device can be selected by selecting the correct "Sub Address", belonging to that device.

When a device is connected correctly, the name and ID of the device will be shown in the info field and the text of the "Connect Device" button will change to "Disconnect Device".

The "Hardware" and the "Baud Rate" fields will be disabled as only one hardware interface can be selected at the time.

The "Connected Devices" list view will be updated with information about the connected device.

Hardware:	ASCII	\sim	Channel	Device Name	Device Id	Device Version
Baud Rate:	115200	~				
COM Port 1:	COM1	~	Sub Addres	s 1: 1 v	. (Connect Device
COM Port 2:	COM1	~	Sub Addres	is 2: 2 ~	· (Connect Device
COM Port 3:	COM3	~	Sub Addres	is 3: 1 ~	· (Connect Device
COM Port 4:	COM4	~	Sub Addres	is 4: 0 ~	· (Connect Device

Connect Dev	ices					
Hardware:	ASCII	\sim	Channel	Device Name	Device Id	Device Version
			01	LDM64	6416	0305
Baud Rate:	115200		02	LDB152	1520	0140
			03	LDB152	1520	0140
				•		
COM Port 1:	COM1	\sim	Sub Addre	ss 1: 0 ~	Dis	sconnect Device
COM Port 2:	00M2		Sub Addro	cc 2: 1	Di	aconnect Douise
COMPORT2.	COM3	\sim	Sub Addre	55 2.	Dis	Sconnect Device
COM Port 3:	COM3		Sub Addre	ss 3: 2 ~	Dis	sconnect Device
COM Port 4:	COM4	~	Sub Addre	ss 4: 0 ~	C	connect Device
	D : 100		1500			
	Device: LDB	152 with Id:	1520 conne	cted.		



Modbus RTU:

To select an H&B device using Modbus RTU as interface, select the Hardware type: "Modbus RTU".

Select the correct baud rate for the device.

Select the COM port to which the device is connected.

If more than one H&B device is connected to the same COM port, a specific device can be selected by selecting the correct "Sub Address", belonging to that device.

When a device is connected correctly, the name and ID of the device will be shown in the info field and the text of the "Connect Device" button will change to "Disconnect Device".

The "Hardware" and the "Baud Rate" fields will be disabled as only one hardware interface can be selected at the time.

The "Connected Devices" list view will be updated with information about the connected device.

Hardware:	Modbus RTU	~	Channel	Device Name	Device Id	Device Version
Baud Rate:	115200	~				
COM Port 1:	COM1	~	Sub Addres	ss 1: 0 ~	(Connect Device
COM Port 2:	COM3	~	Sub Addres	ss 2: 1 ~	(Connect Device
COM Port 3:	COM3	~	Sub Addres	ss 3: 2 ~	(Connect Device
COM Port 4:	COM4	~	Sub Addres	ss 4: 0 ~	C	Connect Device

Connect Devi	ces					
Hardware:	Modbus RTU	\sim	Channel 02	Device Name LDB152	Device Id 1520	Device Version 0140
Baud Rate:	115200	\sim	03	LDB152	1520	0140
COM Port 1:	COM1	~	Sub Addres	ss 1: 0 ~		Connect Device
COM Port 2:	COM3	\sim	Sub Addre	ss 2: 1 ~		Disconnect Device
COM Port 3:	COM3	~	Sub Addre	ss 3: 2 ~		Disconnect Device
COM Port 4:	COM4	~	Sub Addre	ss 4: 0 ~		Connect Device
	Device: LDB15	2 with Id:	1520 conne	cted.		



CANopen:

To select an H&B device using CANopen as interface, select the Hardware type: "CANopen".

Select the correct baud rate for the device.

Select the "CAN Bus", normally an USB bus, to which the device is connected.

If more than one H&B device is connected to the same "CAN Bus", a specific device can be selected by selecting the correct "Address", belonging to that device.

When a device is connected correctly, the name and ID of the device will be shown in the info field and the text of the "Connect Device" button will change to "Disconnect Device".

The "Hardware" and the "Baud Rate" fields will be disabled as only one hardware interface can be selected at the time.

The "Connected Devices" list view will be updated with information about the connected device.

Hardwara	CANenen		Observat	Davias Nama	Device Id	Device Mension
naluwale.	CANopen	~	Channel	Device Name	Device Id	Device version
Baud Rate:	500000	~				
CAN Bus:	USBBUS1	~				
Address 1:	1	~	Sub Addres	ss 1: 0 ~	C	Connect Device
Address 2:	1	~	Sub Addres	ss 2: 0 ~	C	Connect Device
Address 3:	1	~	Sub Addres	ss 3: 0 ~	C	Connect Device
Address 4:	1	~	Sub Addres	ss 4: 0 ~	(Connect Device
					1	

Connect Devi	ices					
Hardware:	CANopen	\sim	Channel	Device Name	Device Id	Device Version
			01	LDM64	6410	0305
Baud Rate:	500000	\sim	02	LDM64	6414	0306
			03	LDM64	6410	0305
CAN Bus:	USBBUS1	\sim	04	LDM64	6416	0305
Address 1: Address 2:	2	~	Sub Addres	ss 1: 0	Die	sconnect Device
Address 3:	3	~	Sub Addres	ss 3: 0	Dis	sconnect Device
Address 4:	8 Device: LDM64	¥ with Id: 6	Sub Addres	ss 4: 0		SCONNECT DEVICE



3 **Commands View**

The "Commands View" dialog is selected from one of the up to four device channel group boxes by selecting the "Commands View" button individually.

In the "Commands View" dialog the command parameters valid for the currently selected H&B device can be examined.

If a command parameter is writeable, it's also possible to change the current value of the command parameter.

Not all the available command parameters in the different command groups are represented in the "Commands View" dialog, such as the commands performing data streaming when they are called, like SN and SG, but most of the relevant and editable commands are represented.

Use the Terminal View for access of special command parameters not supported by the "Commands View".

mmand Overview								
command Group	Command Name	Command	Min Value	Max Value	Туре	Access	Protection	Description
heckweigher	Start Delay	SD	0	65535	Int32	RW	Std	SD - Start Delay
heckweigher	Measure Time	MT	0	3000	Int32	RW	Std	MT - Measuring Time
heckweigher	Get Average	GA	0	65535	Single	R	Std	GA - Get Average - returns the current average wei
heckweigher	Trigger Edge	TE	0	1	Int32	RW	Std	TE - Trigger Edge * selects rising or falling edge trig
heckweigher	Trigger	TR	0	0	Boolean	W	Std	TR - Start the measuring cycle in the same way as t
heckweigher	Trigger Level	TL	0	999999	Int32	RW	Std	TL - Trigger level
heckweigher	ReTrig Window	RW	0	65535	Int32	RW	Std	RW - Set the Retrig window
heckweigher	ReTrigger Time	Π	0	65535	Int32	RW	Std	TT - Set the Re-Trigger time
heckweigher	Hold Time	HT	0	65535	Int32	RW	Std	HT - Set the hold time
heckweigher	Tare Window	TW	0	65535	Int32	RW	Std	TW - Set the tare window
heckweigher	Tare Time	TI	0	65535	Int32	RW	Std	TI - Set the tare time
heckweigher	Delta Time	DT	0	65535	Int32	RW	Std	DT - Delta time
heckweigher	ReTrig Stop	TS	0	65535	Int32	RW	Std	TS- Set the retrig stop
ommunication	Set Address	AD	0	255	Int32	RW	Std	AD - Read/modify the address (0-255)
ommunication	Set Baudrate	BR	9600	460800	Int32	RW	Std	BR - Read/modify the baudrate
ommunication	Duplex Mode	DX	0	1	Int32	RW	Std	DX - Select half(0) or full(1) duplex communication
ommunication	Transmit Delay	TD	0	255	Int32	RW	Std	TD - Set the transmit time
igitalIO	Read Input	IN	0	111	String	R	Std	IN - Read the status of the input channels
initallO	Cat Output	10	0	1111	Otring		C14	IO Dead/Medify the statue of the sutput shannels
mmand Groups	C	ommand Names	6					Dialogs
ommand Group		Command Nam	e Co	mmand		Current \	/alue	Calibration Dialog
alibration		Delta Time		DT			50	outplated Plateg
heckweigher		Get Average		GA			0.00	
ommunication		Hold Time		HT			0	Filter / Tare
igital IO		Measure Time		MT			200	
		Datia Chan		TC		G	5525	O-monitor Han

0

0

0

100

Reload All

Help on SD

Write Only

100

Π

SD

ΤI

TW

TR

TE

TL

ReTrigger Time

Start Delay

Tare Window

Trigger Edge

Trigger Level

Tare Time

Trigger

Motion

Setpoints

Standard

Weight

Zeroing

Terminal View

Values Log View

Exit



3.1 Command Overview

In the "Command Overview" list view, all the commands for the available command groups are listed.

The main characteristic and functionality description for each command can be found in this list.

Not all available commands are represented in the "Command Overview" list view, such as the streaming commands SN and SG as mentioned earlier.

By clicking on a command description in the "Command Overview" list view, the command group to which the command belongs will be highlighted in the "Command Group" list view.

All the commands belonging to the highlighted command group will be listed in the "Command Names" list view. The selected command will also be highlighted in the "Command Names" list view.

By double clicking on a command description in the "Command Overview" list view, an online help web page describing the characteristics for the selected command will appear. Remark: The help option requires internet connection.

Command Group	Command Name	Command	Min Value	Max Value	Туре	Access	Protection	Description
Checkweigher	Start Delay	SD	0	65535	Int32	RW	Std	SD - Start Delay
Checkweigher	Measure Time	MT	0	3000	Int32	RW	Std	MT - Measuring Time
Checkweigher	Get Average	GA	0	65535	Single	R	Std	GA - Get Average - returns the current average wei
Checkweigher	Trigger Edge	TE	0	1	Int32	RW	Std	TE - Trigger Edge * selects rising or falling edge trig
Checkweigher	Trigger	TR	0	0	Boolean	W	Std	TR - Start the measuring cycle in the same way as t
Checkweigher	Trigger Level	TL	0	999999	Int32	RW	Std	TL - Trigger level
Checkweigher	ReTrig Window	RW	0	65535	Int32	RW	Std	RW - Set the Retrig window
Checkweigher	ReTrigger Time	Π	0	65535	Int32	RW	Std	TT - Set the Re-Trigger time
Checkweigher	Hold Time	HT	0	65535	Int32	RW	Std	HT - Set the hold time
Checkweigher	Tare Window	TW	0	65535	Int32	RW	Std	TW - Set the tare window
Checkweigher	Tare Time	TI	0	65535	Int32	RW	Std	TI - Set the tare time
Checkweigher	Delta Time	DT	0	65535	Int32	RW	Std	DT - Delta time
Checkweigher	ReTrig Stop	TS	0	65535	Int32	RW	Std	TS- Set the retrig stop
Communication	Set Address	AD	0	255	Int32	RW	Std	AD - Read/modify the address (0-255)
Communication	Set Baudrate	BR	9600	460800	Int32	RW	Std	BR - Read/modify the baudrate
Communication	Duplex Mode	DX	0	1	Int32	RW	Std	DX - Select half(0) or full(1) duplex communication
Communication	Transmit Delay	TD	0	255	Int32	RW	Std	TD - Set the transmit time
DigitalIO	Read Input	IN	0	111	String	R	Std	IN - Read the status of the input channels
DisitallO	Cat Autaut	10	0	1111	Otring		014	IO Dead/Madify the statue of the sutmut shannals

3.2 Command Groups

0-----

By clicking on a command group description in the "Command Groups" list view, the selected command group will be highlighted and all the commands belonging to the highlighted command group will be listed in the "Command Names" list view. The first command in the selected command group will also be

The first command in the selected command group will also be highlighted in the "Command Overview" list view.

Command Group	
Calibration	
Checkweigher	
Communication	
Digital IO	
EEPROM	
Filter	
Motion	
Setpoints	
Standard	
Weight	
Zeroing	



3.3 Command Names

The "Command Names" list view contains all the commands belonging to the currently selected command group.

If a command parameter is readable, the current value of the command parameter will be displayed in the "Current Value" field of the "Command Names" list view.

By selecting the "Reload All" button, all the readable command parameter values will be reloaded from the selected device.

Command Name	Command	Current Value	
Delta Time	DT	50	
Get Average	GA	0.00	
Hold Time	HT	0	
Measure Time	MT	200	
ReTrig Stop	TS	65535	
ReTrig Window	RW	65535	
ReTrigger Time	Π	0	
Start Delay	SD	100	
Tare Time	TI	0	
Tare Window	TW	0	
Trigger	TR	Write Only	
Trigger Edge	TE	1	Reload All
Trigger Level	TL	100	
			Help on SD

By selecting the command help button or double clicking on a command in the "Command Names" list view, an online help web page describing the characteristics for the selected command will appear. The help option requires internet connection.

If a command parameter is writeable, the "Write" or "Write Value" button is enabled.

If a command parameter is a Boolean writeable but requires no value to be sent with the command parameter, only the "Write" button with no value field will be enabled.

Command Names			
Command Name	Command	Current Value	
Delta Time	DT	50	
Get Average	GA	0.00	
Hold Time	HT	0	Write
Measure Time	MT	200	
ReTrig Stop	TS	65535	
ReTrig Window	RW	65535	
ReTrigger Time	Π	0	
Start Delay	SD	100	
Tare Time	TI	0	
Tare Window	TW	0	
Trigger	TR	Write Only	
Trigger Edge	TE	1	Reload All
Trigger Level	TL	100	Neidau All
			Help on TR



If a command parameter is writeable and requires a parameter value to be written together with the command, the "Value" text field is enabled and having the value of the current command parameter displayed. If the command parameter value in the "Value" text field is modified by user, the "Write Value" and the "Save Value" buttons will be enabled. The modified value can now be written or saved to the device by selecting the "Write Value" or the "Save Value" button as explained below.

Command Names			
Command Name	Command	Current Value	Value: 150
Delta Time	DT	50	
Get Average	GA	0.00	
Hold Time	HT	0	Write Value
Measure Time	MT	200	
ReTrig Stop	TS	65535	Save Value (WP)
ReTrig Window	RW	65535	
ReTrigger Time	Π	0	
Start Delay	SD	100	
Tare Time	TI	0	
Tare Window	TW	0	
Trigger	TR	Write Only	
Trigger Edge	TE	1	Reload All
Trigger Level	TL	100	Noida Air
			Help on MT

If it's possible to save a command value to the EEPROM after it's written to the device, the "Save Value" button will be visible with the name of the save command by which the value will be saved to the EEPROM.

Not all command parameters can be saved to the EEPROM. In these cases, the "Save Value" button will not be visible.

By selecting the "Write Value" button, the modified command value, will be written to the device. A written value will not be saved to the EEPROM before the "Save Value" button is selected.

By selecting the "Save Value" button the written command will be stored in the EEPROM of the device.

All the values belonging to a specific save command will be stored to the EEPROM, when selecting the "Save Value" button.

If changed values are not saved to the EEPROM of the device, the original values stored in the EEPROM will be restored when the device is powered off /on. So, if modified command parameter values are only written but not saved, the modified values are lost when power is removed from the device. This way it's possible to escape from a messy situation where the command parameters status of the device is unclear.



For the writeable command parameters in the calibration group, a "Calibrate Enable" command must be sent to the device before the parameter value of a command can be changed.

By selecting the "Calibrate Enable" button, a calibrate enable command will be sent to the device.

Command Name	Command	Current Value 🔺	Value:
Absolute Value	AV	-127	
Calibrate Enable	CE	1	
Decimal Position	DP	2	Write Value
Display Step	DS	1	
Factory Cal Value	FV	890420	Save Value (CS)
Factory Default	FD	Write Only	
Firmware Type	FT	0	
Init Zero	ZI	0	
Installation Zero	IZ	Write Only	
Lin. Clear	LC	Write Only	Calibrate Enable
Multi Range	MR	0	
Nonvolatile Zero	ZN	0	Reload All
Output Format	OF	0	Neidad All
Save Calibration	CS	Write Only	
Set Maximum	CM	999999 ~	Help on DP

After the "Calibration Enable" command is sent, a given value of a writeable command in the calibration group can be changed and written to the device.

Command Name	Command	Current Value 🔺	Value: 3
Absolute Value	AV	-128	
Calibrate Enable	CE	1	
Decimal Position	DP	2	Write Value
Display Step	DS	1	
Factory Cal Value	FV	890420	Save Value (CS)
Factory Default	FD	Write Only	
Firmware Type	FT	0	
Init Zero	ZI	0	
Installation Zero	IZ	Write Only	
Lin. Clear	LC	Write Only	
Multi Range	MR	0	
Nonvolatile Zero	ZN	0	Reload All
Output Format	OF	0	Robad All
Save Calibration	CS	Write Only	
Set Maximum	CM	999999 ~	Help on DP



After a command parameter value is written, the "Calibrate Enable" button becomes visible again and must be selected before another command parameter value can be modified.

The changed calibration values can be saved to the EEPROM of the H&B device by selecting the "Save Value (CS)" button. All the changed calibration values will be stored to the EEPROM of the device.

After a calibration value is saved by selecting the "Save Value (CS)" button, the "Calibrate Enable" TAC value is increased by +1.

Select the "Reload All" button to see the changed TAC value. The new TAC value is the value of the CE command.

If the changed calibration values are not saved to the EEPROM, the original values stored in the EEPROM will be restored when the device is powered off /on. So, if the calibration values are only written but not saved, the value of the command is lost when power is removed from the device. This way it's possible to escape from a messy situation where the command parameters status of the device is unclear.

Command Name	Command	Current Value 🔺	Value:
Absolute Value	AV	-128	
Calibrate Enable	CE	1	
Decimal Position	DP	3	Write Value
Display Step	DS	1	
Factory Cal Value	FV	890420	Save Value (CS)
Factory Default	FD	Write Only	K
Firmware Type	FT	0	
Init Zero	ZI	0	
Installation Zero	IZ	Write Only	
Lin. Clear	LC	Write Only	Calibrate Enable
Multi Range	MR	0	
Nonvolatile Zero	ZN	0	Reload All
Output Format	OF	0	1 Cload All
Save Calibration	CS	Write Only	
Set Maximum	CM	999999 ~	Help on DP



3.4 Dialogs

In the "Commands View" dialog there are several shortcut buttons by which other dialogs can be accessed.

If zero and span calibration is to be performed, or the value of the "Decimal Position", is to be changed, it's recommended that the special dialog "Calibration Dialog" is used.

For changing filter command values, and setting tare, it's recommended that the special dialog "Filter / Tare" is used.

For setting up communication parameters for serial communication devices, the "Communication" dialog can be used.

For reading and writing "raw" parameter values to and from a device, the "Terminal View" dialog can be used.

For viewing, saving, or printing all the command parameter values for the currently selected device, the "Values Log View" dialog can be used.

For detailed information on how to use the different dialogs, refer to the sections covering these issues.

Dialogs
Calibration Dialog
Filter / Toro
Fillel / Tale
Communication
Terminal View
Values Log View



4 Calibration Dialog

The "Calibration Dialog" accessed from the "Commands View" dialog, is covering the most common calibration procedures.

Besides the calibration description in this manual, the "DOP 4 Quick Start Manual" has a "Device Calibration Walkthrough" section which may also be useful.

HB Calibration Dialog for DAD143		×
Weight Status Filter and Motion Net: 18.123 FM - Filter Mode: 0: TTR	Calibration Parameters	CL-Set Minimum: -30000
Gross: 18.127 FL - Filter Value	AG - Absolute Gain (mV/V): 0.1941	CM1 - Set Maximum 1: 30000
Cut-off (Hz):	AG - Absolute Gain Display: 20000	CM2 - Set Maximum 2: 0
Signal Stable: NR - No Motion Range: 10 NT - No Motion Time (ms): 400	DP - Decimal Point: 3: As 123.456 ~	CM3 - Set Maximum 3: 0
Calibration Counter	DS - Display Step: 1 increment ~	ZI - Init Zero: 0
IAC: 31 Write All Save All	MR - Multi Range: 0: Multi Interval 🗸	ZR - Zero Range: 100
Calibrate by Load Calibrate by Parameters	TN - Tare Volatile: 0: Volatile ~	TM - Tare Mode: 0
Calibrate Scale by Load	ZN - Zero Volatile: 0: Volatile ~	ZM - Zero Mode: 0
Span (Gain) Increments: 20000 CZ - Calibrate Zero	FT - Firmware: 0: Standard ~	ZT - Zero Track: 1
Min. Span - Zero Value: CG - Calibrate Span	Write Changed Parameters	
IZ - Installation Zero	CS - Save Calibration Help on	CZ Exit

The "Calibration Dialog" consists of several sections covering different aspects of zero / span calibration.

4.1 Weight Status

The "Weight Status" group box keeps an ongoing updated status of different weight command values from the "Weight" commands group, used for confirmation and weight status during the calibration procedure.

A stable signal from the load cell is indicated by a green square and an unstable signal is indicated by a red square. The sensitivity for having a stable signal can be adjusted by the "No Motion" command parameters and the Filter value.

Weight Status	Weight Status
Net: 18.123	Net: 12.696
Gross: 18.127	Gross: 14.989
Samp: 56787	Samp: 52098
Signal Stable:	Signal Stable:

4.2 Calibration Counter

The "Calibration Counter" group box contains the current TAC value. The TAC value is increased by one when calibration command values are saved with the "Save Calibration" command.

Calibration Counter			
TAC: 31			



4.3 Filter and Motion

The "Filter and Motion" group box contains some of the command parameter values from the "Filter" commands group and the "Motion" commands group. The represented command parameters are to be used when adjustments to the values of these commands are needed due to calibration problems such as an unstable scale during calibration.

Filter and Motion	Filter and Motion
FM - Filter Mode: 0: IIR ~	FM - Filter Mode: 0: IIR ~
FL - Filter Value	FL - Filter Value
Cut-off (Hz):	Cut-off (Hz):
NR - No Motion Range: 1	NR - No Motion Range: 10
NT - No Motion Time (ms): 1000	NT - No Motion Time (ms): 100
Write All Save All	Write All Save All

The value of the "No Motion Range" command can be increased to accept a wider range of scale instability (The range of accepted change of increments during the calibration measurement).

The value of the "No Motion Time" command can be decreased having a shorter balance period (The period in which the scale must be stable enough to fulfill the calibration).

The value of the filter level determines the 3 dB cut-off frequency and settling time. A high filter value (e.g., 8) results in a steadier scale weight value and a low one (e.g., 0) gives a more dynamic scale weight value, which can be more difficult to calibrate on.

4.3.1 Write Settings

To use the changed filter and motion settings for further calibration it necessary to write the changed values. By selecting the "Write All" button, the changed filter and motion values are written for further use, but not saved. If the values are only written, but not saved, the value of the settings is lost when power is removed from the device.

4.3.2 Save settings

If the changed filter and motion settings are to be used after device power down/up, it's necessary to save the settings into the EEPROM of the device. By selecting the "Save All" button, the changed filter and motion values are saved into the EEPROM of the device.



4.4 Calibration methods

A calibration can be performed by a weight load on a scale or by entering calibration data manually.

4.4.1 Calibrate by Load method

By default, when entering the Calibration Dialog, the calibration method is set to "Calibrate by Load".

Calibrate by Load	O Calibrate by Parameters
-------------------	---------------------------

The "Calibrate Scale by Load" group box is enabled and the "AZ – Absolute Zero" and the "AG – Absolute Gain" fields are set to "Read Only" as shown in the figure below.

HB Calibration Dialog for DAD143			×
Weight Status	Filter and Motion	Calibration Parameters	
Net: 18.123	FM - Filter Mode: 0: IIR ~	AZ - Absolute Zero (mV/V): 0.0368	CI - Set Minimum: -30000
Gross: 18.127	FL - Filter Value Cut-off (Hz): 3: 4 ~	AG - Absolute Gain (mV/V): 0.1941	CM1 - Set Maximum 1: 30000
Samp: 56787	NR - No Motion Range: 10	AG - Absolute Gain Display: 20000	CM2 - Set Maximum 2: 0
Signal Stable:	NT - No Motion Time (ms): 400	DP - Decimal Point: 3: As 123.456 v	CM3 - Set Maximum 3: 0
Calibration Counter		DS - Display Step: 1 increment v	ZI - Init Zero: 0
TAC: 31	Write All Save All	MR - Multi Range: 0: Multi Interval	ZR - Zero Range: 100
 Calibrate by 	Load O Calibrate by Parameters	TN - Tare Volatile: 0: Volatile ~	TM - Tare Mode: 0
Calibrate Scale by Load		ZN - Zero Volatile: 0: Volatile v	ZM - Zero Mode: 0
Span (Gain) Increments:	20000 CZ - Calibrate Zero	FT - Firmware: 0: Standard ~	ZT - Zero Track: 1
Min. Span - Zero Value:	CG - Calibrate Span	Write Changed Parameters	
	IZ - Installation Zero	CS - Save Calibration Help or	n CZ Exit

The calibration method "Calibrate by Load" is described in section covering the "Calibration by Weight Load".



4.4.2 Calibrate by Parameters method

When the "Calibrate by Parameters" radio button is selected, calibration values can be entered manually in the "Calibration Parameters" group box.

Calibrate by Load
 Calibrate by Parameters

The "Calibrate Scale by Load" group box is disabled and the "AZ – Absolute Zero" and the "AG – Absolute Gain" fields are now enabled and set to read / Write mode, as shown in the figure below.

HB Calibration Dialog for DAD143			×
Weight Status Net: -0.003	Filter and Motion FM - Filter Mode: 0: IIR ~	Calibration Parameters AZ - Absolute Zero (mV/V): 0.0173	CI - Set Minimum: -30000
Gross: -0.002	FL - Filter Value Cut-off (Hz): 3: 4 ~	AG - Absolute Gain (mV/V): 0.1955	CM1 - Set Maximum 1: 30000
Samp: 4544 Signal Stable:	NR - No Motion Range: 10	AG - Absolute Gain Display: 20000	CM2 - Set Maximum 2: 0
Calibration Counter	NT - No Motion Time (ms): 400	DS - Display Step: 1 increment v	ZI - Init Zero: 0
TAC: 31	Write All Save All	MR - Multi Range: 0: Multi Interval v	ZR - Zero Range: 100
\bigcirc Calibrate by	/ Load Calibrate by Parameters	TN - Tare Volatile: 0: Volatile ~	TM - Tare Mode: 0
Calibrate Scale by Load		ZN - Zero Volatile: 0: Volatile ~	ZM - Zero Mode: 0
Span (Gain) Increments:	20000 CZ - Calibrate Zero	FT - Firmware: 0: Standard v	ZT - Zero Track: 1
Min. Span - Zero Value:	 CG - Calibrate Span 	Write Changed Parameters	
	IZ - Installation Zero	CS - Save Calibration Help o	n CZ Exit

Setting the calibration parameters is described in the section covering the "Calibration Parameters".



4.5 Calibration by Weight Load

The "Calibrate Scale by Load" group box consists of several buttons and command fields to be used during a zero / span calibration session.

IMPORTANT! When doing a calibration on devices having a "seal switch" such as the DAD141 and the LDM64 device, remember to remove the seal switch if one is present.

4.5.1 Zero Calibration

A calibration session starts by a calibration of the zero point.

Before calibrating the zero point, be sure that the scale is unloaded.

When ready for zero calibration, select the "CZ - Calibrate Zero" button. A message reminder about unloading the scale will appear.	Calibrate Scale by Load Span (Gain) Increments: 20000	CZ - Calibrate Zero
point calibration will start.	Min. Span - Zero Value: 5% ~	CG - Calibrate Span
When the zero-point calibration is started, the ongoing calibration will be indicated by a yellow message box in the left bottom of the "Calibrate Scale by Load" group box.	CALIBRATING ZERO. WAIT!	IZ - Installation Zero
If the zero-point calibration	Calibrate Scale by Load	
calibration will be indicated with a green message box in the left	Span (Gain) Increments: 20000	CZ - Calibrate Zero
bottom of the "Calibrate Scale by Load" group box.	Min. Span - Zero Value: 5% ~	CG - Calibrate Span
	CALIBRATING ZERO DONE.	IZ - Installation Zero

By examine the "Weight Status" group box the zero-point weight values can be studied.

If the zero-point calibration fails, it will be indicated by a red message box in the left bottom of the "Calibrate Scale by Load" group box. A failing zero-point calibration can be caused by a too unstable scale. Try to adjust the parameters of the "Filter and Motion" group box as explained earlier in this section and retry.

Calibrate Scale by Load	
Span (Gain) Increments: 20000	CZ - Calibrate Zero
Min. Span - Zero Value:	CG - Calibrate Span
CALIBRATING ZERO FAILED!	17 - Installation Zero



4.5.2 Span Calibration

After the zero point has been calibrated successfully the span calibration procedure can be executed.

Before the span calibration is started, the span increments can be adjusted by changing the value of the "Span (Gain) Increments:" field, so the value matches the weight to be loaded when the span calibration is to be executed. The span increments are the weight value without the decimal point.

Also, the minimum percentage, by which the sample value must be increased when the scale is loaded with the span weight, can be adjusted by changing the value of the "Min. Span – Zero Value:" drop down box.

The minimum difference in the sample value between zero load and span load can be calculated by taking the maximum sample value for the device under calibration an calculate the percentage value indicated in the "Min. Span – Zero Value" drop box.

Using the LDU 78.1 as an example, the maximum samples value is 262143. So, when using a 5% calculation, the minimum allowed difference between zero and span is 13103 samples and 5242 when the value is set to 2%

Calibrate Scale by Load Span (Gain) Increments: 10000	CZ - Calibrate Zero
Min. Span - Zero Value: 5% ~	CG - Calibrate Span
CALIBRATING Z DONE. 5%	IZ - Installation Zero

When the different values for the span calibration is set, the span calibration is ready to start.

Be sure to load the scale with the correct weight load.

When ready for span calibration, select the "CG - Calibrate Span" button.



When the span calibration is started, the ongoing calibration will be indicated by a yellow message box in the left bottom of the "Calibrate Scale by Load" group box.

Calibrate Scale by Load	
Span (Gain) Increments: 20000	CZ - Calibrate Zero
Min. Span - Zero Value:	CG - Calibrate Span
CALIBRATING SPAN.	
WAIT!	17 - Installation Zero

If the span calibration succeeded, the successful calibration will be indicated with a green message box in the left bottom of the "Calibrate Scale by Load" group box.

Calibrate Scale by Load	
Span (Gain) Increments: 20000	CZ - Calibrate Zero
Min. Span - Zero Value: 5% 🗸	CG - Calibrate Span
CALIBRATING ZERO DONE.	17 - Installation Zoro
	12 - Mistalidüüli Zelü

By examine the "Weight Status" group box the span weight values can be studied.

If the span calibration fails, it will be indicated by a red message box in the left bottom of the "Calibrate Scale by Load" group box.

A failing span calibration can be caused by a too unstable scale. Try to adjust the parameters of the "Filter and Motion" group box as explained earlier in this section and retry.

Calibrate Scale by Load	
Span (Gain) Increments: 20000	CZ - Calibrate Zero
Min. Span - Zero Value: 🗸 🗸 🗸	CG - Calibrate Span
CALIBRATING SPAN FAILED!	IZ - Installation Zero



4.6 Calibration Parameters

From the "Calibration Parameters" group box, the values of various calibration command parameters can be examined and changed.

The Calibration dialog is general for all types of H&B devices, so not all the calibration parameters are valid for all devices. Calibration parameters not valid for a given device will be disabled.

When changing one of the calibration parameters, the "Write Changed Parameters" button becomes enabled and by selecting the button the values of the changed parameters will be written to the device. The values will not be saved to the EEPROM, so if the changed calibration parameters are to be used after device power off / on, it's necessary to save the settings into the EEPROM of the device by selecting the "CS - Save Calibration

Calibration Parameters				
AZ - Absolute Zero	(mV/V): 0.0173	CI - Set Minimum:	-30000	
AG - Absolute Gain	(mV/V): 0.1955	CM1 - Set Maximum 1:	30000	
AG - Absolute Gain	Display: 20000	CM2 - Set Maximum 2:	0	
DP - Decimal Point:	3: As 123.456 v	CM3 - Set Maximum 3:	0	
DS - Display Step:	1 increment v	ZI - Init Zero:	0	
MR - Multi Range:	0: Multi Interval 🗸	ZR - Zero Range:	100	
TN - Tare Volatile:	0: Volatile ~	TM - Tare Mode:	0	
ZN - Zero Volatile:	0: Volatile ~	ZM - Zero Mode:	0	
FT - Firmware:	0: Standard v	ZT - Zero Track:	1	
Write Changed Parameters				

selecting the "CS - Save Calibration" button.

4.6.1 Set Linearization Points for the LDU69 and the LDB15x device

If the connected device is a LDU69 or a LDB15x device, the button "Set Linearization Points" is visible in the "Calibration Parameters" group box.

By selecting the "Set Linearization Points" button the "Set Linearization Points" dialog will be opened.

From this dialog it's possible to inspect and correct more than the two normal calibration points set by the CZ and CG commands.

To add a new linearization point, select the next free fields with the dashes on it and enter the new values. Select the "Write All" button and a new set of points can be entered and so on.

By selecting the "Clear Lin. Points" button, the linearization points setting can be set back to the default setup.

Remember to save the settings in the main calibration dialog.

	arameters	Set Lineariza	ation Points
Sot	HB Set Linearization Points	-	- 🗆 X
Set		mV / V	Display
~e	LN1 - Linearization point 1:	0.01912	0
nd	LN2 - Linearization point 2:	4.65017	500000
	LN3 - Linearization point 3:		
n	LN4 - Linearization point 4:		
	LN5 - Linearization point 5:		
.16	LN6 - Linearization point 6:		
lit	LN7 - Linearization point 7:		
	Write All		Help
	Clear Lin. Points		Exit
	Save settings using 'CS - S	ave Calibra	tion' button.



4.6.2 Set Firmware Types for DAD14x, LDB15x and LDM64

If the connected device is a DAD14x, LDB15x or a LDM64 device, the field "FT – Firmware Type" is visible in the "Calibration Parameters" group box.

FT - Firmware:	0: Standard	~	FT - Firmware:	1: Filling ~
ET Firmwara	2: Mass Flow	~	ET Eirmuoro	2: Drop Filling
FT - FIIIIWale.	2. Md551 10W	<u> </u>	FT - Firmware:	3: Drop Filling V

By changing the value of this field, it's possible to change the current firmware type of the device.

For the DAD141 / DAD142 device, the available firmware types are: Standard (Checkweigher), Filling, Drop Filling and Mass flow firmware types.

For the LDM64 / LDB151 / LDB 152 / DAD143 device, the available firmware types are Standard (Checkweigher) and Filling firmware types.

When changing the firmware type value, the device must be removed from the channel list in the "Device Selector" dialog and reinserted after the value is stored in the Calibration dialog. The value should only be changed when the Calibration dialog is opened from "Commands View" via the "Device Selector" dialog.

Also, the device itself should be turned off and on after the change of firmware type.

4.6.3 Save Calibration

If the changed calibration parameters are to be used after device power off / on, it's necessary to save the settings into the EEPROM of the device. By selecting the "CS - Save Calibration" button, the changed calibration parameters are saved into the EEPROM of the device.

|--|

The internal TAC value of the device will be increased by one.



4.7 Help on Calibrate Command Parameters

If the user is connected to the internet, help on the different command parameters of the Calibration dialog can be obtained by selecting the "Help on (Command)" button. On the "Calibrate Zero" or the "Calibrate Gain" help web page, the "Calibration Procedure" link can be selected for more information and hints for the calibration procedure.

On the "Filter Value" help web page, the "General filter description" link can be selected for more information on the different values of filter setting commands.



5 Filter / Tare

The "Filter / Tare" dialog is a combined dialog for setting command parameter values belonging to the Filter and motion groups and to set and reset the current tare and zero values.

The "Filter / Tare" dialog can be accessed from the "Commands View" dialog.

н	B Filter / Tare for DAD143		×
	Filter and Motion		7
	FM - Filter Mode: 0: IIR	NR - No Motion Range: 20	
	FL - Filter Value Cut-off (Hz):	V NT - No Motion Time (ms): 400	
	UR - Update Rate 0: 1 Devisor:	Vrite All Save All	
	Weight Status Net: 4.648	Tare and Zero RT - Reset Tare SZ - Set Zero	
	Gross: 2.660	ST - Set Tare RZ - Reset Zero	
	Tare: -1.988	SP - Set Preset Tare Preset Value: 0	
	Signal Stable:	Help on ST Exit	

By examine the "Weight Status" group box the changes in the net and gross weight values reflected by the changes of tare settings can be studied.

The Tare settings cannot be saved to the EEPROM. So, the tare settings will disappear after device power down/up.

The Set Preset Value will be stored directly to the EEPROM of the device.



5.1 Filter and Motion

The "Filter and Motion" group box contains the command values from the "Filter" commands group and the "Motion" commands group for easy setup of these parameters.

The "Filter and Motion" group box is also meant to be a help when setting tare in an unstable scale environment.

Filter and Motion		
FM - Filter Mode:	0: IIR \sim	NR - No Motion Range: 1
FL - Filter Value Cut-off (Hz):	1: 18 ~	NT - No Motion Time (ms): 1000
UR - Update Rate Devisor:	0:1 ~	Write All Save All

The value of the "No Motion Range" command can be increased to accept a wider range of motion increments when setting tare.

The value of the "No Motion Time" command can be decreased having a shorter balance period (The period in which the scale must be stable enough to fulfill the tarring scale max motion demands).

The value of the filter level determines the cut-off frequency and settling time. A high filter value (e.g., 8) results in a steadier scale weight value and a low one (e.g., 0) gives a more dynamic scale weight value, which can be more difficult to do tarring on.

Filter and Motion			
FM - Filter Mode:	0: IIR v	NR - No Motion Range: 2	0
FL - Filter Value Cut-off (Hz):	3: 4 ~	NT - No Motion Time (ms): 40	0
UR - Update Rate Devisor:	0: 1 ~	Write All Save All	

5.1.1 Write Settings

By selecting the "Write All" button, the changed filter and motion values are written for further use, but not saved. If the values are only written, but not saved, the value of the settings is lost when power is removed from the device.

5.1.2 Save settings

If the changed filter and motion settings are to be used after device power down/up, it's necessary to save the settings into the EEPROM of the device. By selecting the "Save All" button, the changed filter and motion values are saved into the EEPROM of the device.



5.2 Weight Status

The "Weight Status" group box keeps an ongoing updated status of different weight command values from the "Weight" commands group, used for confirmation and weight status during the tarring procedure.

A stable signal from the load cell is indicated by a green square and an unstable signal is indicated by a red square. The sensitivity for having a stable signal can be adjusted by the "No Motion" parameters.



5.3 Tare Settings

By selecting the buttons "RT – Reset Tare" or "ST – Set Tare" the tare for the scale can be reset or set.

	RT - Reset Tare	
ST - Set Tare	ST - Set Tare	

5.3.1 Reset Tare

When selecting the "RT- Reset Tare" button, the weighing signal returns to gross mode. So, after tare reset, both the net and gross weight will have the same values.

By examine the "Weight Status" group box the user will see that the net and gross values are equal, and the tare value is zero.

A stable signal from the load cell is indicated by a green square and an unstable signal is indicated by a red square. The sensitivity for having a stable signal can be adjusted by the "No Motion" parameters.

5.3.2 Set Tare

When ready for setting the tare, select the "ST - Set Tare" button.

If the tare setting succeeded, the tare setting will be reflected by the weight values in the "Weight Status" group box.

If the tare setting failed, a message box will appear saying that the tare setting went wrong. The unsuccessful setting can be caused by a too unstable scale. Try to adjust the parameters of the "Filter and Motion" check box as explained earlier in this section and retry.







SZ - Set Zero

RZ - Reset Zero

5.4 Zero Settings

By selecting the buttons "RZ – Reset Zero" or "SZ – Set Zero" the zero point for the scale can be reset or set.

5.4.1 Reset Zero

When selecting the "RZ- Reset Zero" button, the weighing signal returns to gross mode. So, after zero reset, both the net and gross weight will have the same values.

By examine the "Weight Status" group box the user will see that the net and gross values are equal and the zero value is zero.

A stable signal from the load cell is indicated by a green square and an unstable signal is indicated by a red square. The sensitivity for having a stable signal can be adjusted by the "No Motion" parameters.

0.196
0.196
0.000

5.4.2 Set Zero

When ready for setting the zero point, select the "SZ - Set Zero" button.

If the zero-point setting succeeded, the zero-point setting will be reflected by the weight values in the "Weight Status" group box.

If the zero-point setting failed, a message box will appear saying that the zero-point setting went wrong. The unsuccessful setting can be caused by a too unstable scale. Try to adjust the parameters of the "Filter and Motion" check box as explained earlier in this section and retry.

Weight Status Net: 0.000 Gross: -0.001 Tare: 0.000 Signal Stable:

5.5 Help on (Command)

If the user is connected to the internet, selecting the help button "Help on (Command)" will give access to help on the currently highlighted command button or command text field. On the "Filter Value" help web page, the "General filter description" link can be selected for more information on the different values of filter setting commands.



6 Communication

The "Communication" button opens different communication setup dialogs for devices connected through a serial interface, depending on the currently selected device.

The "Communication Setup" dialog for setting up communication parameters for the device will be opened by selection of the button.

The "Communication" dialog can be accessed from the "Commands View" dialog.

6.1 Communication Setup Dialog

From the "Communication Setup" dialog, communication command parameters can be changed for the selected device which must be a device connected through a serial interface.

6.1.1 General Parameters

In the "General Parameters" group box, the "Communication" list view contains the communication command parameters valid for the currently selected device. The number of command parameters can vary depending on the currently selected device. By selecting on of parameters for editing, the parameter and its current value will be reflected in the "Edit Parameter Value" group box.

HB Communication Setup for LDM64			×
General Parameters		Edit Parameter Value)
Communication		Value:	0
Parameter	Value		
COM Baud Rate	115200	Source	Value
Sub Address	0	Save	value
Duplex Mode	Full Duplex		
Transmit Delay	0		
CAN Baud Rate	500000	Help	on AD
CAN Address	2		
TPD01 Decimator	1	Softwa	re Reset
		Continu	10110301
		E	xit

6.1.2 Edit Parameter Value

In the "Edit Parameter Value" group box the value of the selected communication parameter can be changed. Select the "Save Value" button to save the changed parameter value to EEPROM.

6.1.3 Software Reset

Selecting the "Software Reset" button resets the device and returns to the caller of the Commands View dialog. The device may have to be reconnected after the reset.

6.1.4 Help on (Command)

If the user is connected to the internet, selecting the help button "Help on (Command)" will give access to the help page for the currently highlighted communication parameter.



6.2 ASCII to Modbus RTU Interface change

From the "Communication Setup" dialog it is possible to change from ASCII interface to Modbus RTU interface if these interfaces are supported by the device.

The figures below show how to change an ASCII interface to Modbus RTU interface.

Communication Parameter Value COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duplex Transmit Delay 00 CAN Baud Rate 500000 CAN Baud Rate 500000 CAN Address 1 TPD01 Decimator 1 Interface ASCI ommunication Setup for LDB151 1 communication 2 Con Baud Rate 115200	Value: ASCII Save Value Help on NS Software Reset Exit Edit Parameter Value Value: Value: Modbus RTU Save Value Save Value
Parameter Value COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duplex Transmit Delay 00 CAN Baud Rate 500000 CAN Baud Rate 500000 CAN Address 1 TPD01 Decimator 1 Interface ASCI ammunication Setup for LDB151 1 eneral Parameters 2 Communication 2 Parameter Value COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duplex Transmit Delay 0 CAN Baud Rate 500000	Edit Parameter Value Value Kalue: Modbus RTU Save Value Save Value
COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duplex Transmit Delay 0 CAN Baud Rate 500000 CAN Address 1 TPD01 Decimator 1 Interface ASCI ammunication Setup for LDB151 seneral Parameters Communication Parameter Value COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duplex Transmit Delay 0 CAN Baud Rate 500000	Edit Parameter Value Value Value Value Save Value Edit Parameter Value Value Save Value
Sub Address 2 Duplex Mode Full Duplex Transmit Delay 0 CAN Baud Rate 500000 CAN Address 1 TPD01 Decimator 1 Interface ASCI ammunication Setup for LDB151 eneral Parameters Communication Parameters Value COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duplex Transmit Delay 0 CAN Baud Rate 500000	Edit Parameter Value Value: Modbus RTU Save Value
Duplex Mode Full Duplex Transmit Delay (C CAN Baud Rate 500000 CAN Address (T TPD01 Decimator (T Interface ASCI ommunication Setup for LDB151 (C communication (C Parameter Value COM Baud Rate 115200 Sub Address (C Duplex Mode Full Duplex Transmit Delay (C CAN Baud Rate 500000	Edit Parameter Value Value: Modbus RTU Save Value
Transmit Delay (C CAN Baud Rate 500000 CAN Address TPD01 Decimator TD01 Decimator TD01 Decimator TO Interface ASCI communication Setup for LDB151 eneral Parameters Communication Parameter Value COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duples Transmit Delay (C CAN Baud Rate 500000	Help on NS Software Reset Exit Edit Parameter Value Value: Modbus RTU Save Value
CAN Baud Rate 500000 CAN Address 500000 TPD01 Decimator 67 Interface ASCI ommunication Setup for LDB151 eneral Parameters Communication Parameter Value COM Baud Rate 115200 Sub Address 22 Duplex Mode Full Duples Transmit Delay 00 CAN Baud Rate 500000	Edit Parameter Value Value: Modbus RTU
CAN Address CONTRACTOR	Edit Parameter Value Value: Modbus RTU Save Value
TPD01 Decimator T Interface ASCI ommunication Setup for LDB151 eneral Parameters Communication Parameter COM Baud Rate 0115200 Sub Address Duplex Mode Full Duples Transmit Delay CAN Baud Rate	Edit Parameter Value Value: Modbus RTU Save Value
Interface ASCI AS	Edit Parameter Value Value: Modbus RTU Save Value
eneral Parameters Communication Parameter COM Baud Rate Sub Address Duplex Mode Transmit Delay CAN Baud Rate Sub Adata	Edit Parameter Value Value: Modbus RTU Save Value
eneral Parameters Communication Parameter COM Baud Rate Sub Address Duplex Mode Transmit Delay CAN Baud Rate	Edit Parameter Value Value: Modbus RTU Save Value
eneral Parameters Communication Parameter Value COM Baud Rate 115200 Sub Address 2 Duplex Mode Full Duple: Transmit Delay 0 CAN Baud Rate 500000	Edit Parameter Value Value: Modbus RTU Save Value
CommunicationParameterValueCOM Baud Rate115200Sub Address2Duplex ModeFull DupleTransmit Delay0CAN Baud Rate500000	Value: Modbus RTU Save Value
ParameterValueCOM Baud Rate115200Sub Address2Duplex ModeFull DuplexTransmit Delay0CAN Baud Rate500000	Save Value
COM Baud Rate115200Sub Address2Duplex ModeFull DuplexTransmit Delay0CAN Baud Rate500000	Save Value
Sub Address2Duplex ModeFull DuplexTransmit Delay0CAN Baud Rate500000	Save Value
Duplex ModeFull DuplexTransmit Delay0CAN Baud Rate500000	c
Transmit Delay (CAN Baud Rate 50000)	
CAN Baud Rate 500000	
	Help on NS
CAN Address	
TPD01 Decimator	Coffuero Decet
Interface ASCI	Software Reset
	Exit
ommunication Setup for LDB151	
eneral Parameters	Edit Parameter Value
Communication	Value: Modbus RTU
Parameter Value	
COM Baud Bate 115200	
Sub Address	Save Value
Duplex Mode Full Dupley	
Transmit Delay	
CAN Baud Pate 50000	Help on NS
TDD01 Designator	
Interface Medice DT	Software Reset
Interlace ModDUS RTC	



6.3 Modbus RTU to ASCII Interface change

If Modbus RTU interface is selected and the device has repowered, the text of the communication button will be changed from "Communication" to "ASCII Interface" as shown in the figure below.

Command Group	Command Name	Command	Min Value	Max Value	Туре	Access	Protection	Description
Calibration	Calibrate Enable	CE	0	65535	Int32	RW	Std	CE - Set the calibration functions to the enabled st
Calibration	Set Minimum	CI	-999999	0	Int32	RW	Tac	CI - Set the minimum allowable output value
Calibration	Set Maximum	CM	1	999999	Int32	RW	Tac	CM - Set the maximum allowable output value
Calibration	Display Step	DS	1	500	Int32	RW	Tac	DS - Set the display step size
Calibration	Decimal Position	DP	0	6	Int32	RW	Tac	DP - Set the decimal point position
Calibration	Factory Cal Value	FV	0	0	Int32	R	Tac	FV - Read the Factory Calibration Value
Calibration	Zero Track	ZT	0	255	Int32	RW	Tac	ZT - Enables or disables the zero tracking
Calibration	Save Calibration	CS	0	0	Boolean	W	Tac	CS - Save the calibration values
Calibration	Factory Default	FD	0	0	Boolean	W	Tac	FD - Load factory default
Calibration	Absolute Value	AV	-33000	33000	Int32	R	Std	AV - Get the absolute value point
Calibration	Installation Zero	IZ	0	0	Boolean	W	Tac	IZ - Installation Zero.
Calibration	Init Zero	ZI	0	999999	Int32	RW	Tac	ZI - Init Zero Range.
Calibration	Zero Range	ZR	0	999999	Int32	RW	Tac	ZR - Zero Range.
Calibration	Tare Non Volatile	TN	0	1	Int32	RW	Tac	TN - Set/Clear non-volatile tare.
Calibration	Nonvolatile Zero	ZN	0	1	Int32	RW	Tac	ZN - Set/Clear non-volatile zero
Calibration	Tare Mode	TM	0	1	Int32	RW	Tac	TM - Tare Mode.
Calibration	Set Maximum1	CM1	1	999999	Int32	RW	Tac	CM1 - Set the maximum allowable output value #1.
Calibration	Set Maximum2	CM2	0	999999	Int32	RW	Tac	CM2 - Set the maximum allowable output value #2.
Colibration	Cat Maximum2	0140	0	000000	1-+22		Taa	OM2 Cat the maximum allowable autout value #2

Command Groups	Command Names				Dialogs
Command Group Calibration	Command Name	Command	Current Value		Calibration Dialog
Checkweigher					
Digital IO					Filter / Tare
EEPROM					
Filter					ASCII Interface
Motion					
Setpoints					Torminal View
Standard					
Weight					
Zeroing					Values Log View
				Reload All	
				Command Get Help	Exit

Selecting the "ASCII Interface" button will change the current Modbus RTU interface to ASCII interface.

The following message will be displayed:

HB Reset?	Х	
The current Modbus RTU interface will be changed to ASCII interface for the current device?		
The Commands View dialog will be closed and the device must hereafter be disconnected in the main dialog.		
Power the device off/on and then reconnect it.		
Yes No		



7 The Terminal View

The "Terminal View" dialog is a dialog tool for sending raw parameter commands to the device and to examine the received command responses.

The "Terminal View" dialog comes in 3 versions, one version for devices using Serial COM having an ASCII interface as communication interface, one version for devices using CANopen as communication interface and one version for devices using Serial COM having RTU Modbus as communication interface.

The "Terminal View" dialog can be accessed from the "Commands View" dialog.

7.1 Terminal View dialog, the ASCII version

The "Terminal View" dialog for serial COM devices having an ASCII interface consists of a "Command Request" group box containing the tools for sending command parameter requests, and a "Command Response" group box containing the tools for displaying the command responses in the "Command Response" text box.

HB Terminal View for LDB151	-		×
Command Response			
			x
□ Show Request □ Line Numbers	(lear	
Command Request			
☑ Clear request field after send	9	end	
Use timer Repeat each:	1. se	C	~
Help on Commands	Exit		



7.1.1 Command request

By typing a command name in the "Command Request" text field with or without a parameter value and selecting the "Send" button, the entered command string will be sent to the H&B device as an ASCII string.

The response if any will be displayed in the "Command Response" text box.

See the help section on how to get a list of valid serial COM command names, if connected to the internet.

There is no check for the validity of the entered command. The entered ASCII string will be sent to the device as is.

A command sent without a parameter value will normally, by the device, be interpreted as a value read request for	Command Request		
	Clear request field after send		
	Use timer Repeat each: 1. sec	\sim	
A command sent with a parameter value will normally, by the device, be interpreted as a write value request for that command.	Command Request MT 150 ☑ Clear request field after send Send		
	Use timer Repeat each: 1. sec	\sim	

By checking the "Clear request field after send" check box, the content of the command line in the "Command Request" text field will be cleared after the command is sent.

By checking the "Use timer" check box, the	Command Request			
Request" text field will be sent repeatedly with a repeat time as specified by the timer	GG			
value in the "Repeat each" drop down box.	Clear request field after send		Send	
It's not possible to check the "Use timer" check box, if the "Clear request field after send" check box is checked.	☑ Use timer	Repeat each: 1.	Sec	~

By selecting the "Send" button, with the "Use timer" check box checked, the repeated send of the current command in the "Command Request" text box will be started. The text of the "Send" button will be changed to "Stop" and selecting this button will stop the

repeated send of the current command in the "Command Request" text box.

You can still while the timer is running change the repeat time by which the current command will be sent. By selecting the "Stop" button or removing the check from the "Use Timer" check box, the timer will be stopped.

Command Request		
GG		
Clear request field after send		Stop
☑ Use timer	Repeat each:	1. sec ~



7.1.2 Command response

In the "Command Response" text box, all the input ASCII strings received from the current H&B device will be displayed as received without any filtering.

If the "Show Request" check box is checked, the ASCII string entered in the "Command Request" text field will be displayed in the "Command Response" text box when sent.

If the "Line Numbers" check box is checked, line numbers will be added in front of the displayed text strings.

Selecting the "Clear" button will clear the "Command Response" text box.

 Command Response

 0001: Request: MT

 0002: M+00000

 0003: Request: MT 150

 0005: Request: MT

 0006: M+00150

 0007: Request: ID

 0008: D:1510

7.1.3 Help

If the user is connected to the internet, selecting the help button "Help" will give access to a list of common commands which can be used in the "Command Request" text field.



7.2 Terminal View dialog, the CANopen version

The "Terminal View" dialog for CANopen interface devices consist of a "Command Request" group box containing the tools for sending and receiving command parameter requests, and a "Command Response" group box containing the tools for displaying the command responses.

By checking the "All Values as Hex" check box, the different parameter values will be displayed as hex values.

nmand Re	quest				Command Response
Main Ind.	Sub Ind.	Access	Description	Command Name ^	Read request: 2100,08
2100	01	rw	Analog Source		Read result : 150
2100	02	rw	Analog High		Send reguest: 2100,00 200
2100	03	rw	Analog low		Read request: 2100,08
2100	04	rw	Filter setting	_FL_FilterValue	Read result : 200
2100	05	rw	Filter factor		
2100	06	rw	Output status	_IO_Output	
2100	07	rw	Input mask	_IN_ReadInput	
2100	08	rw	Measuring time	_MT_MeasureTime	
2100	09	rw	Filter mode	_FM_FilterMode	
2100	0A	rw	No motion range	_NR_NomotionRange	
2100	0B	rw	No motion time	_NT_NomotionTime	
2100	0C	rw	Output mask	_IM_Inputmask	
2100	0D	rw	Tare		
2100	0E	rw	Start delay	_SD_StartDelay	
2100	0F	rw	Trigger egde	_TE_TriggerEdge	
2100	10	rw	Trigger level	_TL_TriggerLevel	
2100	11	rw	Update rate	_UR_UpdateRate	
2100	12	rw	Zero tracking		
2100	13	rw	dTime	_DT_DeltaTime	
2100	14	rw	Zero Nonvolatile	_ZN_ZeroNonvolatile	
2100	15	rw	Analog Mode	_AM_AnalogMode	
2100	16	rw	Pre Filter	_PF_PreFilter	
2100	17	rw	Preset Tare	_SP_SetPresetTare	
2100	18	rw	web Server Enable	_SE_ServerEnable	
2200	00	ro	Number of Objects in this module		
2200	01	rw	Pre fill mode	_PD1_PreFillMode	



7.2.1 Command request

The "Command Request" group box contains a list view with the complete set of CANopen commands supported by the H&B CANopen interface-based devices.

Each line in the list view contains the definition and information for a given CANopen command defined by a "Main Index" and a "Sub Index" value. If the "Command Name" field contains a name, it's the name of the corresponding H&B general device command.

By selecting a line in the "Command Request" list view, the value of the command parameter will, if possible, be read and displayed in the "Command Response" text box. The main and sub index values will also be read to the corresponding index fields.

If a valid integer value is entered in the "Value of Index" text field, and the "Write Index Value" button is selected, the value will, if possible, be written to the device as a parameter with the CANopen command index selected by the "Main Index" and "Sub Index" fields. The response if any will be displayed in the "Command Response" text box.

A main and sub index can manually be defined in the corresponding fields and by selecting the "Read Index Value" button, the value of the defined index will be read and placed in the "Value of Index" Field and in the "Command Response" text box.

Main Ind.	Sub Ind.	Access	Description	Command Name ^
2100	01	rw	Analog Source	
2100	02	rw	Analog High	
2100	03	rw	Analog low	
2100	04	rw	Filter setting	_FL_FilterValue
2100	05	rw	Filter factor	
2100	06	rw	Output status	_IO_Output
2100	07	rw	Input mask	_IN_ReadInput
2100	08	rw	Measuring time	_MT_MeasureTime
2100	09	rw	Filter mode	_FM_FilterMode
2100	0 A	rw	No motion range	_NR_NomotionRange
2100	0B	rw	No motion time	_NT_NomotionTime
2100	0C	rw	Output mask	_IM_Inputmask
2100	0D	rw	Tare	
2100	0E	rw	Start delay	_SD_StartDelay
2100	0F	rw	Trigger egde	_TE_TriggerEdge
2100	10	rw	Trigger level	_TL_TriggerLevel
2100	11	rw	Update rate	_UR_UpdateRate
2100	12	rw	Zero tracking	
2100	13	rw	dTime	_DT_DeltaTime
2100	14	rw	Zero Nonvolatile	_ZN_ZeroNonvolatile
2100	15	rw	Analog Mode	_AM_AnalogMode
2100	16	rw	Pre Filter	_PF_PreFilter
2100	17	rw	Preset Tare	_SP_SetPresetTare
2100	18	rw	web Server Enable	_SE_ServerEnable
2200	00	ro	Number of Objects in this module	
2200	01	rw	Pre fill mode	_PD1_PreFillMode
Main Inde	ex (hex):	:	2100 Read Index Value	Value of Index: 200
	,			

If the user is connected to the internet, selecting the help button "Help on Commands" will give access to a list of common CANopen commands.



7.2.2 Command response

In the "Command Response" text box, all the input and output parameter values for a given command defined by a main index and sub index value received from the current device will be displayed as received or sent.

If the "Show Request" check box is checked, the read or send request for the value of a specific main and sub index is displayed in the "Command Response" text box.

If the "Line Numbers" check box is checked, line numbers will be added in front of the displayed text strings.

Selecting the "Clear" button will clear the "Command Response" text box.

Command Response

Read request: 2100,08 Read result : 150 Send request: 2100,08 200 Send result : 0K Read request: 2100,08 Read result : 200 □ Line Numbers □ Show Request Clear						
Read result : 150 Send request: 2100,08 200 Send result : 0K Read reguest: 2100,08 Read result : 200	Read	request:	2100,08			\sim
Send request: 2100,08 200 Send result : OK Read request: 2100,08 Read result : 200 Line Numbers Show Request Clear	Read	result :	150			
Send result : OK Read request: 2100,08 Read result : 200	Send	request:	2100,08	200		
Read request: 2100,08 Read result : 200 ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓	Send	result :	OK			
Line Numbers ✓ Show Request Clear	Read	request:	2100,08			
□ Line Numbers	кеаа	result :	200			
□ Line Numbers						
□ Line Numbers						
□ Line Numbers Show Request						
□ Line Numbers Show Request Clear						
□ Line Numbers Show Request Clear						
□ Line Numbers Show Request Clear						
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 ✓ Line Numbers ✓ Clear 						
 □ Line Numbers ☑ Show Request 						\sim
 □ Line Numbers ☑ Show Request 						
☑ Line Numbers ☑ Show Request		no Numbers				
☑ Show Request Clear		ne numbers				
✓ Show Request				C	lear	
	⊠ S	how Reques	t			



7.3 Terminal View dialog, the Modbus version

The "Terminal View" dialog for Modbus interface devices consists of a "Command Request" group box containing the tools for sending command parameter requests, and a "Command Response" group box containing the tools for displaying the command responses in the "Command Response" text box.

HB Terminal View for LDB151	_	
Command Response		
		^
		~
□ Show Request	C Response in H	ex
Line Numbers	Clear	
Command Request		
Register Address:	As Hex	
Write out Value:	As Hex	
○ Int16 Value ● Int32 Va	lue	
Write to Register	Read Registe	ər
Help on Commands	Exit	.:

If the user is connected to the internet, selecting the help button "Help on Commands" will give access to a list of valid Modbus indexes.



7.3.1 Command request

In the "Register Address" field a register address for reading or writing is entered. If the "As Hex" checkbox to the right of the "Register Address" field is checked, the field value will be interpreted as a hexadecimal value.

In the "Write out Value" a value to be written to the specified register address is entered. If the "As Hex" checkbox to the right of the "Write out Value" field is checked, the field value will be interpreted as a hexadecimal value.

Command Request		
Register Address:	2412	☑ As Hex
Write out Value:	200	□ As Hex
○ Int16 Value	● Int32 Value	
Write to Registe	er	Read Register

With the radio buttons "Int 16 Value" and "Int 32 Value" the value length of the specified register address is defined as either a 16 bit or 32 bit integer value. Selecting the "Help on Commands" button, the shown Modbus indexes will show the length of the register values.

Selecting the "Write to Register" button will write the value of the "Write out Value" field to the defined register address.

Selecting the "Read Register" button will read the value from the defined register address and show the value in the "Command Response" text box.

The response if any will be displayed in the "Command Response" text box.

7.3.2 Command response

In the "Command Response" text box, all the input and output parameter values for a given command received from the current device will be displayed as read or write results.

If the "Show Request" check box is checked, the read or write request for the value of a register address is displayed in the "Command Response" text box.

If the "Line Numbers" check box is checked, line numbers will be added in front of the displayed text strings.

By checking the "Response in Hex" check box, the different parameter values will be displayed as hex values.

Selecting the "Clear" button will clear the "Command Response" text box.

Command Response	
0001: Read request: 0002: Read result: 1 0003: Write request: 0004: OK writing to: 0005: Read request: 0006: Read result: 2	2412 00 2412, 200 2412 2412 00
Show Request	
☑ Line Numbers	Clear



8 Values Log View

The "Values Log View" dialog is a dialog tool for saving and printing the values of all the valid command parameters for the currently selected device.

The "Values Log View" dialog can be accessed from the "Commands View" dialog.

HB Command Values Log View for LDB151	_		×
Command Values Log			
Command Values Log			
Command values for LDB151 using Modbus RTU		^	
Calibration CE - Calibrate Enable = 3 CI - Set Minimum = -999999 CM - Set Maximum = 999999 DS - Display Step = 1 DP - Decimal Position = 2 FV - Factory Cal Value = 890420 CG - Calibrate Gain = 27765 ZT - Zero Track = 0 AG - Absolute Gain = 2.0002 CV - Calibrate Value = -103 AZ - Absolute Value = -103 AZ - Absolute Zero = 0 ZI - Init Zero = 0 TN - Tare Non Volatile = 0 ZN - Nonvolatile Zero = 0 TM - Tare Mode = 0			
CM1 - Set Maximum1 = 9999999			
CM2 - Set Maximum2 = 0			
CM3 - Set Maximum3 = 0			
MR - Multi Range = 0			
FT - Firmware Type = 0			
Checkweigher SD - Start Delay = 200 MT - Measure Time = 150 GA - Get Average = 0.00 TE - Trigger Edge = 0 TL - Trigger Level = 999999 RW - ReTrig Window = 65535 TT - ReTrigger Time = 0 HT - Hold Time = 0 TW - Tare Window = 0 TI - Tare Time = 0 DT - Delta Time = 50 TS - ReTrig Stop = 65535		Ŷ	
Save Log Print Log Set Font Z Align '='		Exit	

8.1.1 Save Log

By selecting the "Save Log" button, the content of the "Command Values Log" text field can be saved to a disk file either as a plain text file or as a formatted RTF text file to be viewed as a Word document.

8.1.2 Print Log

Selecting the "Print Log" button, the content of the "Command Values Log" text field can be send to a connected printer by selection.

8.1.3 Set Font

Selecting the "Set Font" button, the font and the size of the "Command Values Log" text field content can be adjusted.

8.1.4 Align `='

By checking the "Align '=''' field the content of the "Command Values Log" text field can be adjusted so all of the '=' signs are aligned together.



9 Matrix Calibration

The "Matrix Calibration" dialog is a dialog tool for the calibration the 4 currently selected devices acting as if only one device was connected. The matrix calibration is using a special algorithm which can calibrate 4 load cells as one by moving a calibration weight 4 times around on the surface of a 4 cells scale as illustrated below:



The "Matrix Calibration" dialog can only be accessed if 4 load cells are connected in the "Four Port Viewer" application and is opened by selecting the "Matrix Calibration" button.

Matrix Calibration

When the "Matrix Dialog" is opened, the calibration is done by follow the menu directions step by step.

First thing to define is the value of the total gain increments for the 4 load cells together. The value is defined without a decimal point.

When the increments are entered in the "Total gain increments" field, select the "Use Gain Increments" button to confirm.

HB Calibrate 4 Cells	×	
Set the gain increments value. Select the 'Use Gain Increments' button when done.		
Total gain Increments:	2000	
Use Gain Increments	Done	
Calibrate All Zero	Done	
Calibrate All Part 1	Done	
Calibrate All Part 2	Done	
Calibrate All Part 3	Done	
Calibrate All Part 4	Done	
Save Calibration	Done	
Exit		

The "Done" field will be checked and the "Calibrate All Zero" button will be enabled.

Clear the scale for all weight loads and select the "Calibrate All Zero" button.

HB Calibrate 4 Cells	×	
Empty the scale. Select the 'Calibrate All Zero' button when done.		
Total gain Increments:	2000	
Use Gain Increments	Done 🗹	
Calibrate All Zero	Done	
Calibrate All Part 1	Done	
Calibrate All Part 2	Done	
Calibrate All Part 3	Done	
Calibrate All Part 4	Done	
Save Calibration	Done	
Exit		

All of the 4 load cells will now be zero calibrated.

The "Done" field will be checked and the "Calibrate All Part 1" button will be enabled.

For the next 4 step follow the instructions as described in the instruction field.

Use a weight load which corresponds to the defined total gain increments.

HB Calibrate 4 Cells	×	
Put weight on one side of the scale. Select the 'Calibrate All Part 1' button when done.		
Total gain Increments:	2000	
Use Gain Increments	☑ Done	
Calibrate All Zero	✓ Done	
Calibrate All Part 1	Done	
Calibrate All Part 2	Done	
Calibrate All Part 3	Done	
Calibrate All Part 4	Done	
Save Calibration	Done	
Exit		

When all of the 4 calibration steps are completed, select the "Save Calibration" button and then the "Exit" button to leave the dialog.

You can also just select the "Exit" button if you for some reason don't want to save the calibration.

HB Calibrate 4 Cells	×	
Calibration done. Select the 'Save Calibration' button to save calibration.		
Total gain Increments:	2000	
Use Gain Increments	☑ Done	
Calibrate All Zero	☑ Done	
Calibrate All Part 1	☑ Done	
Calibrate All Part 2	☑ Done	
Calibrate All Part 3	☑ Done	
Calibrate All Part 4	☑ Done	
Save Calibration	Done	
Exit		